

Introduction and Motivation

- Out of date and limited resolution satellite images
- Geographically coordinated data visualization from aerial photography
- Explore applications of Unmanned Aerial Vehicles for collection and mapping of radiation measurements
- Provide more detailed and up-to-date aerial images for accurate radiation mapping

Mission Relevance

- Applications in monitoring and response
- Opportunities for student research
- STEM education in nuclear engineering

Technical Approach

- Inspired Flight IF1200 Heavy Lift Hexacopter carries camera payload for image collection
- Survey planning with QGroundControl
- OpenDroneMap used to create orthophoto and 3D point cloud
- Low-quality images manually sorted out of dataset before running OpenDroneMap
- Fine-tuning drone flight speeds and image timing





Mapping of Ionizing and Non-Ionizing Radiation with an Unmanned Aerial Vehicle **Using Open-Source Software Clay Hudson** Sophomore, University of Michigan Caleb M Bush, Hythem H Beydoun, Ryan A Kim, Jakob R Wiest, Kimberlee J Kearfott

University of Michigan

Results

This work was funded in-part by the Consortium for Monitoring, Technology, and Verification under DOE-NNSA award number DE-NA0003920



Paper visible from 100 m

Orthophoto from **OpenDroneMap**

- Research experience

View of 3D point cloud and textured model in WebODM





Expected Impact

• Provide more relevant aerial photos than are available from satellite imaging • Demonstrate feasibility of open-source tools for aerial mapping and surveying • Displaying multispectral and ionizing radiation data on a single map

MTV Impact

 Workshop presentation opportunity • Student research funding

Conclusion

 High quality aerial photos processed and combined into orthophoto Open-source tools yield satisfactory and promising results without expensive licensing • Small objects identifiable from aerial photos

Next Steps

• Thermal imaging payload for multispectral mapping Ionizing radiation detection payloads • Larger image datasets

